

Statistical research on forming of threaded holes in thin plates

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1. Introduction

Thread machining is widely used operation in various industries; however, it is difficult to tap a hole in thin-walled parts due to the insufficient thickness. Therefore, an additional insert welding operation is required to increase the overall thickness of the wall. In order to avoid this problem, friction drilling along with fluteless tapping can be used. These methods allow to produce threaded holes in thin plates by using special tungsten carbide and HSS tools without cutting edges. Applying this technique, the drilling tool penetrates the material making a hole and simultaneously forming an additional molten flange on the underneath side of the workpiece, which later is tapped using a special taper. The main stages of forming steps of threaded holes are shown in Fig. 1.

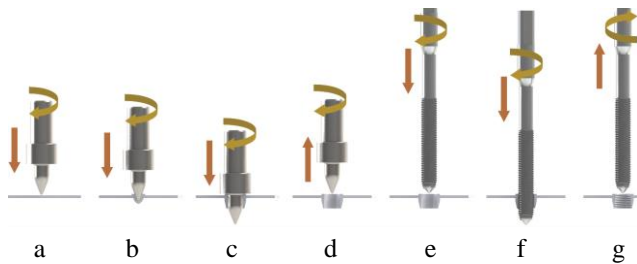


Fig. 1 Stages of hole and thread forming in a thin plate: a – initial contact; b – former-tip penetration into the material; c – material flow and hole forming; d – former withdrawal; e – fast travel of the taper to the workpiece; f – extrusion tapping; g – taper withdrawal

Scientific works on fluteless manufacturing technologies usually deal with tool wear [1-3], the surface quality of produced holes [4, 5] and experimental investigations on the drilling force and moment [6, 7]. Paper [8] investigates the effect of fluteless tapping parameters on the responses: torque, hardness, fill rate, and thrust force of the form tapping process.

However, the fluteless tapping process of holes produced by friction drilling was not widely studied and the influence of machining data on the forces and moments which occurs during the process of drilling and tapping is not yet completely investigated.

This paper presents an investigation of the influence of machining data and workpiece thickness on the force and moment of drilling and tapping during friction forming of threaded holes in thin plates along with a multi-variable linear regression analysis of the results. A proper

adjustment of machining data leads to an increase of forming performance and decrease of tool wear.

2. Experimental technique of the extrusion drilling and tapping

The research on the force and moment during drilling and tapping in thin plates was carried out using DC-01 steel sheets with 1.0 mm and 1.5 in thickness. The mechanical properties of the material are presented in Table 1.

Table 1
Mechanical material properties

Material	Tensile strength, ultimate, MPa	Tensile strength, yield, MPa	Elongation at break, %	Modulus of elasticity, GPa
DC-01 (1.0330)	280	160	28	201

The experimental setup is shown in Fig. 2. The experiments were carried out on a CNC milling machine “DECKEL MAHO DMU-35M” 1 with a “Sinumerik 810D/840D” controller and “ShopMill” software using tungsten carbide fluteless drills with diameters of 5.4 mm and 7.3 mm. The friction contact area ratio (FCAR) and the friction angle the of the drills were 75% and 33°, respectively. High speed steel fluteless tappers of an M6×1.0 mm and M8×1.25 mm were used for tapping. It should be noted that the cross-sections of the working sections of the both



Fig. 2 Experimental setup of the friction drilling and tapping experiments: 1 – milling machine DMU-35 M; 2 – “Kistler” amplifier; 3 – “Kistler” force and torque sensor; 4 – computer; 5 – picoscope

tools are polygonal shaped, in order to ensure better metal flow during the hole forming and tapping.

The axial force and torque were measured using a universal laboratory charge amplifier Kistler type 5018A 2 and a press force sensor Kistler type 9345B 3 mounted on the CNC table. Measuring ranges of the sensor: -10...10 kN for force, -25...25 Nm for torque; sensitivity: ≈ 3.7 pC/N for force, ≈ 200 pC/Nm for torque. The amplifier converts the charge signal from the piezoelectric pressure sensor into a proportional output voltage. The variation of the axial drilling force and torque was recorded to a computer 4 using a "PICOSCOPE 4424" oscilloscope 5 and "PicoScope 6" software.

The holes with 5.4 and 7.3 mm in diameter were formed in the sheets for further tapping of M6 and M8 threads.

3. Results and discussion of the experimental investigation

The results of the investigation of holes forming under different spindle speed and feed are presented in Figs. 3 - 6, of thread tapping ones – in Figs. 7 and 8.

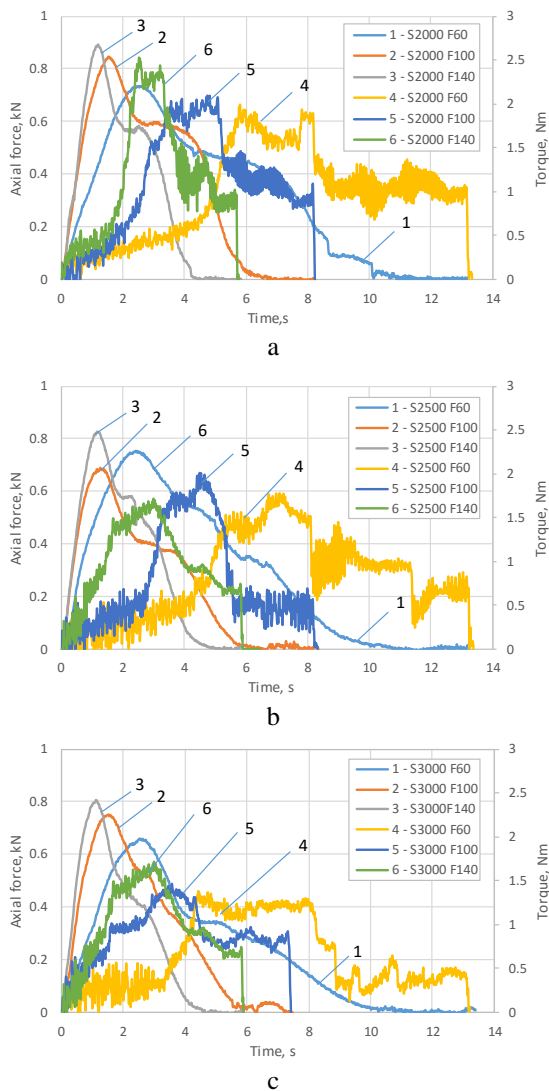


Fig. 3 Drilling force and torque variation during 5.4 mm hole forming on 1.0 mm sheet thickness: a – 2000 rpm; b – 2500 rpm; c – 3000 rpm (1 - 3 axial force; 4 - 6 torque)

Spindle speeds of 2000, 2500 and 3000 rpm were used and for each of them three tool feed rates of 60, 100 and 140 mm/min were assigned in order to investigate the influence of these parameters on the axial hole forming and tapping forces as well as the torque along with a statistical prediction.

The matrix of the drilling and tapping experiments is presented in Table 2.

Table 2 Matrix of the drilling and tapping experiments

Material	Hole diameter, mm	Plate thickness, mm	Drilling		Tapping	
			Spindle speed, rpm	Feed rate, mm/min	Spindle speed, rpm	Feed rate, mm/rev
Steel DC-01	M06-5.4	1.0	2000	60	100	1.0
		1.5	2500	100	200	
	M08-7.3	1.0	3000	140	300	1.25
		1.5				

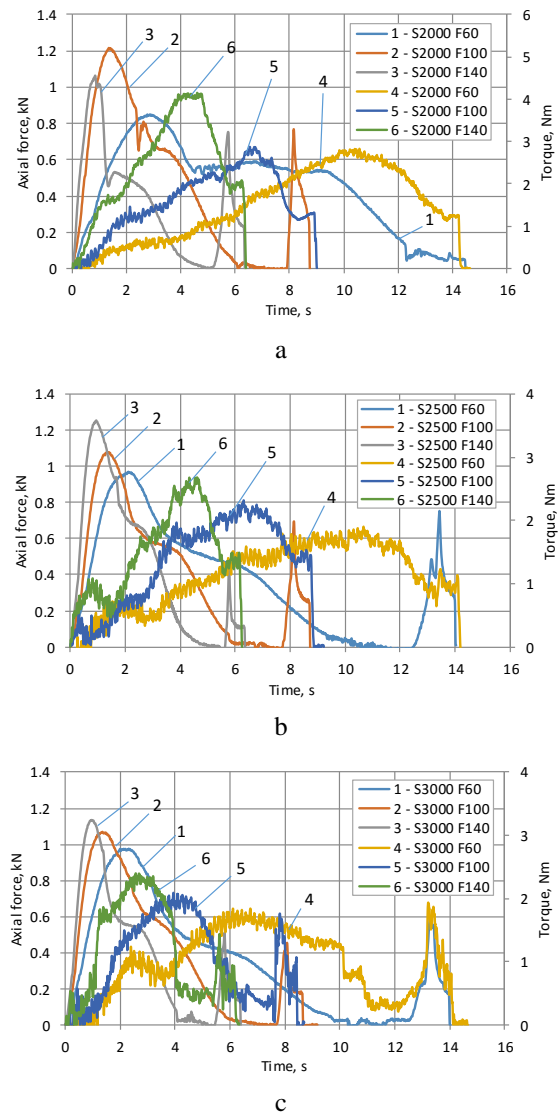


Fig. 4 Drilling force and torque variation during 5.4 mm hole forming on 1.5 mm sheet thickness: a – 2000 rpm; b – 2500 rpm; c – 3000 rpm (1 - 3 axial force; 4 - 6 torque)

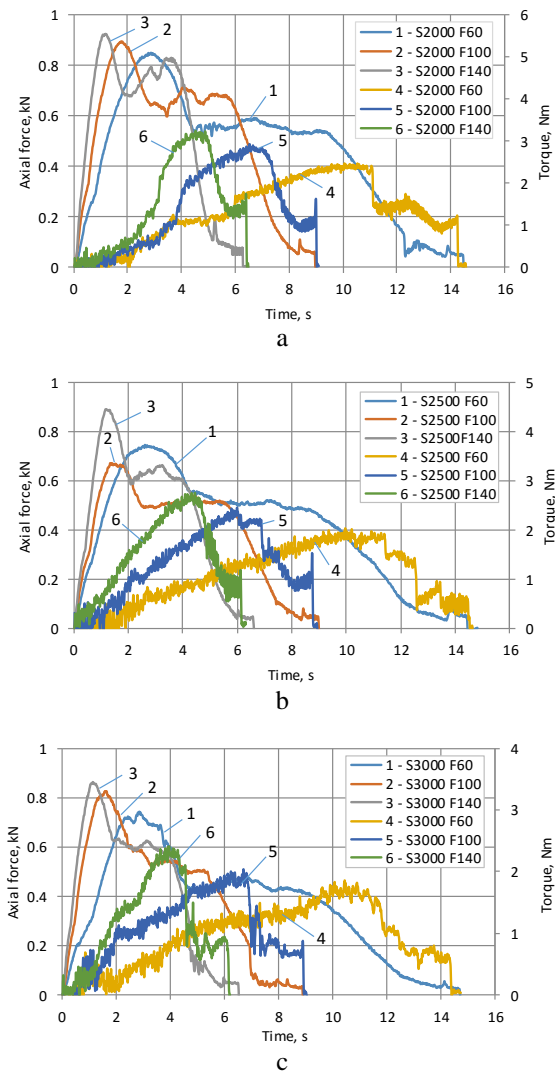


Fig. 5 Drilling force and torque variation during 7.3 mm hole forming on 1.0 mm sheet thickness: a – 2000 rpm; b – 2500 rpm; c – 3000 rpm (1 - 3 axial force; 4 - 6 torque)

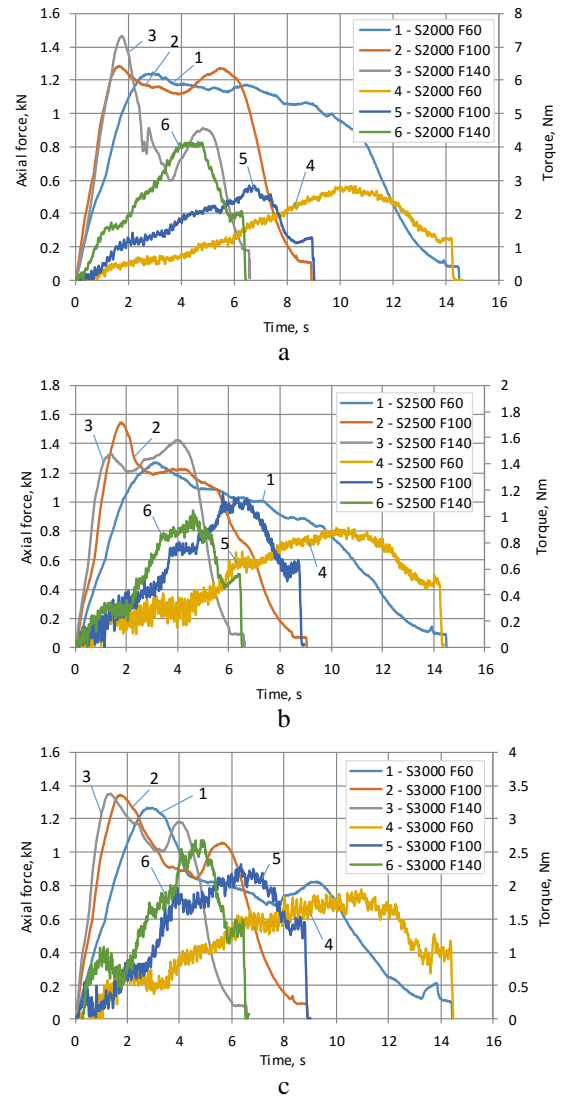


Fig. 6 Drilling force and torque variation during 7.3 mm hole forming on 1.5 mm sheet thickness: a – 2000 rpm; b – 2500 rpm; c – 3000 rpm (1 - 3 axial force; 4 - 6 torque)

The experiment showed that the tool rotational speed has a significant influence on the axial force and torque variation. An analysis of the experimental results showed that the axial force, during the drilling process (from the initial contact until the end of the hole forming), varies in a very wide range. The axial force reaches its maximum value when the conical part of the tool fully penetrates into the plate. When the sheet is pierced, the axial force drastically decreases, meanwhile the torsion moment increases. The maximum torque is reached when the conical part of the tool is fully penetrated into the plate.

The experimental results enabled to conclude that the optimal machining data are spindle speed 2500-3000 rpm and forming feed rate 100 mm/min.

It was observed that the tapping force values are very low (less than 90 N), therefore these results were not presented and discussed. The negative torque values during tapper withdrawal in Fig. 7 and 8 are not presented, because they are very low compared to the tapping torque. When the spindle speed is 2000 rpm, the maximum torque is obtained between 1 and 2 s, after that it gradually decreases. The tapping torque was several times higher than the drilling torque.

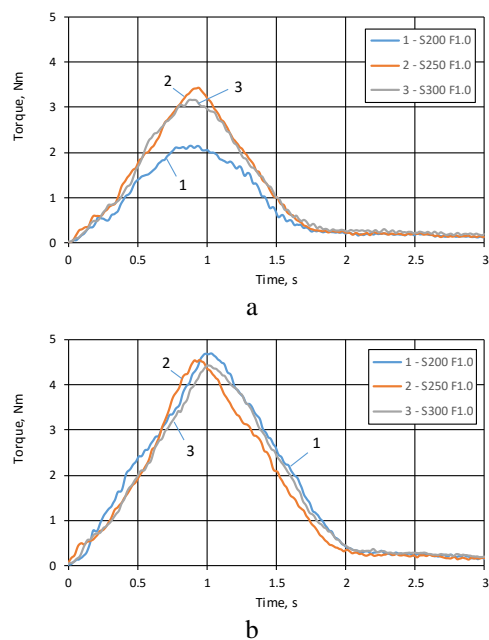


Fig. 7 Tapping torque variation during M6 thread forming: a – 1.0 mm, b – 1.5 mm sheet thickness

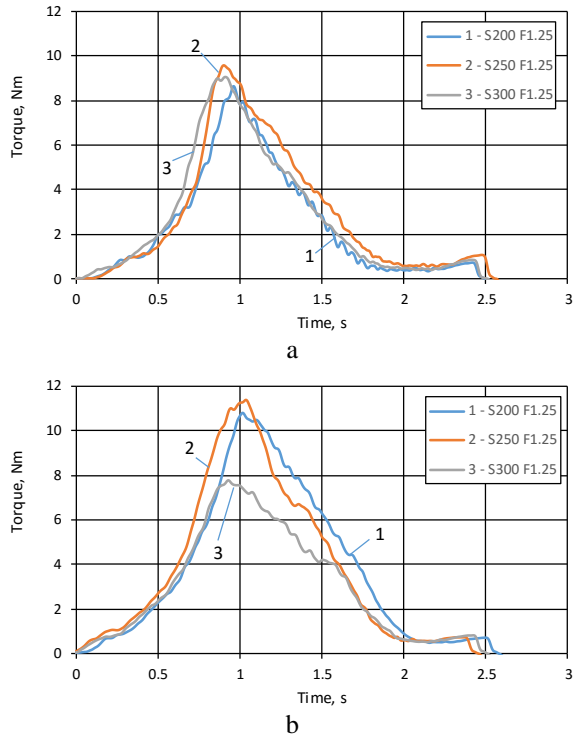


Fig. 8 Tapping torque variation during M8 thread forming: a – 1.0 mm, b – 1.5 mm sheet thickness

4. Multivariable linear regression analysis

The multivariable regression analysis was carried out in order to identify the influence of the drilling and tapping machining data on the maximum axial force F_{dmax} , maximum drilling and tapping torques T_{dmax} , T_{imax} .

Experimental matrix, on which base regression analysis was performed, are presented in Tables 3 and 4.

It was assumed that the intervals of factors variation are tenuous, iterations can be limited by linear approximation

$$Y = a_0 + a_1X_1 + a_2X_2 + a_3X_3 + \dots + a_nX_n, \quad (1)$$

where $a_0, a_1, a_2, a_3, \dots, a_n$ are unknown parameters of the model (regression coefficients); $n = 1, 2, 3, \dots, i$ are the factors of influence; $X_1, X_2, X_3, \dots, X_i$ are independent variables.

Referring to this, a regression analysis was performed making presumption that the drilling force and the torque are stipulated as the entirety of drilling machining data, i.e. spindle rotational speed S , feed rate F , tool diameter D and sheet thickness t and could be expressed by a four variable regression model for F_{dmax} , T_{dmax} and T_{imax} respectively.

The summary output, analysis of variance, parameter values and comparative four variable linear regression analysis for maximal axial drilling force and torque and tapping torque are presented in Tables 5 and 6.

The regression model adequacy was evaluated taking into account the value of the correlation coefficient R^2 (Table 4). A high value of R^2 indicates that the obtained model adequately explains the variation of the forming parameters.

Table 3
Drilling force and torque regression matrix and results

S , rpm	F , mm/min	D , mm	t , mm	F_{dmax} , kN	F_{dmax} , kN	T_{dmax} , Nm	T_{dmax} , Nm
X_1	X_2	X_3	X_4	Y_{exp}	Y_{calc}	Y_{exp}	Y_{calc}
2000	140	5.4	1.0	0.88	0.82	2.40	2.58
	100			0.84	0.75	1.99	2.25
	60			0.77	0.68	1.86	1.92
2500	140	5.4	1.0	0.82	0.79	1.72	2.17
	100			0.69	0.73	1.63	1.83
	60			0.75	0.66	1.68	1.51
3000	140	5.4	1.0	0.80	0.77	1.63	1.74
	100			0.75	0.70	1.40	1.42
	60			0.65	0.63	1.24	1.09
2000	140	5.4	1.5	1.06	1.26	3.94	3.05
	100			1.21	1.19	2.72	2.72
	60			1.09	1.12	2.62	2.39
2500	140	5.4	1.5	1.25	1.24	2.55	2.63
	100			1.08	1.16	2.20	2.30
	60			0.96	1.09	1.81	1.97
3000	140	5.4	1.5	1.33	1.21	2.28	2.21
	100			1.07	1.14	1.94	1.88
	60			0.97	1.07	1.74	1.55
2000	140	7.3	1.0	0.92	0.97	2.96	2.92
	100			0.89	0.90	2.75	2.59
	60			0.85	0.83	2.30	2.27
2500	140	7.3	1.0	0.89	0.94	2.60	2.50
	100			0.67	0.87	2.25	2.17
	60			0.74	0.80	1.91	1.85
3000	140	7.3	1.0	0.86	0.92	2.28	2.08
	100			0.82	0.85	1.88	1.75
	60			0.74	0.77	1.72	1.43
2000	140	7.3	1.5	1.46	1.41	3.83	3.39
	100			1.32	1.33	2.63	3.60
	60			1.24	1.26	2.68	2.73
2500	140	7.3	1.5	1.42	1.38	2.55	2.96
	100			1.54	1.30	2.58	2.64
	60			1.33	1.24	2.01	2.31
3000	140	7.3	1.5	1.35	1.35	2.54	2.55
	100			1.29	1.28	2.19	2.22
	60			1.26	1.21	1.78	1.89

Table 4
Thread tapping experiment matrix and regression results

S , rpm	F , mm/min	D , mm	t , mm	T_{imax} , Nm	T_{imax} , Nm
X_1	X_2	X_3	X_4	Y_{exp}	Y_{calc}
200	1.0	6	1.0	2.13	3.08
250	1.0	6	1.0	3.4	2.84
300	1.0	6	1.0	3.12	2.60
200	1.25	8	1.0	8.41	8.82
250	1.25	8	1.0	9.57	8.58
300	1.25	8	1.0	8.89	8.34
200	1.0	6	1.5	4.65	4.39
250	1.0	6	1.5	4.51	4.15
300	1.0	6	1.5	4.41	3.91
200	1.25	8	1.5	10.82	10.13
250	1.25	8	1.5	11.31	9.89
300	1.25	8	1.5	7.66	9.65

As it is seen from Table 4, a good correlation between the experimental and the predicted values of F_{dmax} , T_{dmax} and T_{tmax} was observed. The analysis showed that the four variable linear regression model with 89% confidence for F_{dmax} , 82% confidence for T_{dmax} and 92 % confidence for T_{tmax} adequately evaluates the magnitude of the forming parameters.

The results of the model validation are presented in Table 5.

Table 5

Regression Statistics

Regression data	F_{dmax}	T_{dmax}	T_{tmax}
Multiple R	0.94	0.90	0.96
R Square	0.89	0.82	0.92
Adjusted R Square	0.88	0.79	0.76
Standard Error	0.09	0.27	1.08
Observations	36	36	12

The model significance was evaluated using the Fisher’s statistical method. From the F -criteria tables [9], under the confidence interval $\alpha = 0.05$, for drilling $F_{0.05} = 2.69$ while for tapping $F_{0.05} = 3.26$. Since the calculated F value for drilling maximum force $F_{calc} = 62.5 \gg F_{0.05} = 2.69$, for drilling torque $F_{calc} = 34.2 \gg F_{0.05} = 2.69$ and for tapping torque $F_{calc} = 29.9 \gg F_{0.05} = 3.26$, the model can be considered as significant and can be used for estimation of the axial force and torque.

Table 6

Analysis of variance (ANOVA)

	df		
	F_{dmax}	T_{dmax}	T_{tmax}
Regression	4	4	4
Residual	31	31	8
Total	35	35	12
F	62.5	34.2	29.9

The coincidence of the experimental and calculated F_{dmax} and T_{dmax} values enabled to conclude that regression model Eq. (1) could be used to optimise friction drilling process for wide spectrum of the structural materials.

The significance of the regression analysis factors was estimated by normalising the factors using these expressions of normalised parameters.

$$X_{in} = \frac{2(X_i - X_{i0})}{(X_{imax} + X_{imin})} \text{ and } X_{i0} = \frac{(X_{imax} - X_{imin})}{2}, \quad (2)$$

where i is the number of factor X ; n is the row number for the each X factor in the column.

The normalised regression coefficients (Table 7) showed that the thickness of the workpiece and the diameter of the tool have the highest influence on the axial drilling force; the tool diameter and the feed rate have the highest influence on the drilling torque, while the sheet thickness has the highest influence on the tapping torque.

Table 7

Normalised regression coefficients

	Regression coefficients		
	F_{dmax}	T_{dmax}	T_{tmax}
Intercept	-0.296	1.41	-12.3
Variable X_1	-0.131	-2.09	-1.21
Variable X_2	0.177	0.82	0
Variable X_3	0.486	1.12	20.9
Variable X_4	1.096	0.22	3.27

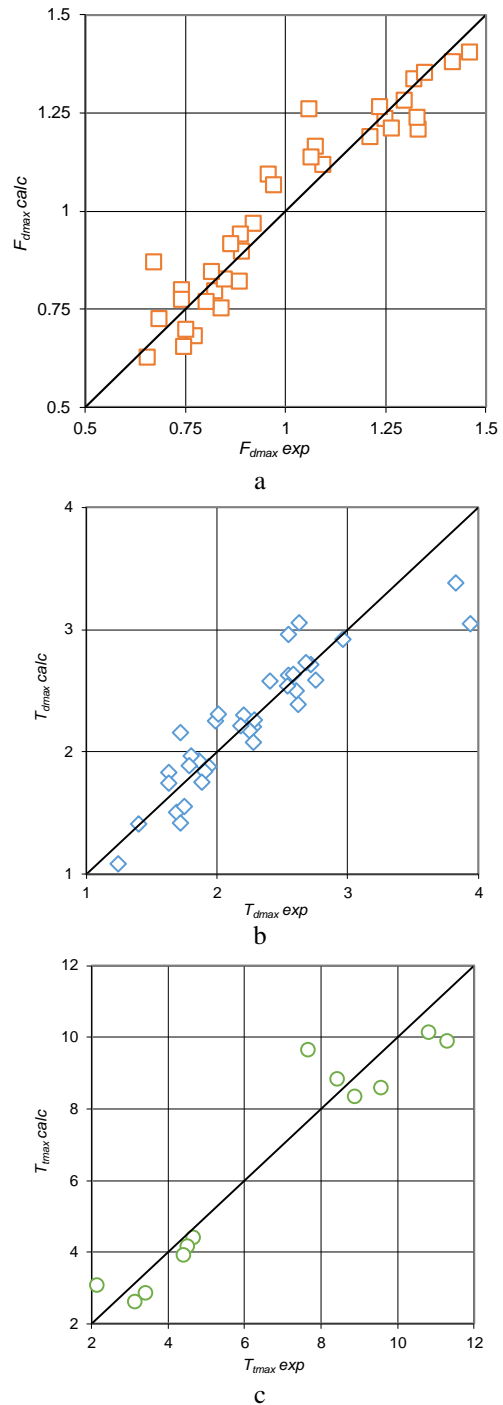


Fig. 9 Statistical evaluation of the holes forming and tapping results: a – drilling axial force; b – drilling torque; c – tapping torque

The regression analysis of thread forming has showed that the feed rate during thread tapping has no influence, because the regression coefficient of this variable is 0 (Table 4). It means that the influence of the tapping parameters on the tapping torque can be approximated by the three variable regression model. The latter model was also verified and the regression statistics as well as the coefficients of the regression model were obtained the same as in the four variables regression.

4. Conclusions

An experimental analysis along with a multifactor regression analysis of holes and threads forming in thin plates were carried out and the axial force and torque variations were measured under different hole forming and tapping parameters.

The regression model adequacy was evaluated taking into account the value of the correlation coefficient R^2 . A good correlation between the experimental and the predicted maximum values of axial force F_{dmax} , drilling torque T_{dmax} and tapping torque T_{imax} was observed.

The regression analysis showed that the calculated F value for drilling maximum force $F_{calc} = 62.5 \gg F_{0.05} = 2.69$, for drilling torque $F_{calc} = 34.2 \gg F_{0.05} = 2.69$ and for tapping torque $F_{calc} = 29.9 \gg F_{0.05} = 3.26$, the model can be considered as significant and can be used for estimation of the axial force and torque.

The normalised regression coefficients showed that the thickness of the workpiece and the diameter of the tool have the highest significance on the axial drilling force; the most significant drilling parameter on the drilling torque is the tool diameter and feed rate, while the highest influence on tapping torque has the sheet thickness.

The research allows to predict optimal parameters for holes and treads forming in thin plates in order to optimise the drilling and tapping force along with the torque and, as a consequence, to decrease tool wear and extend the lifetime of the tools.

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STATISTICAL RESEARCH ON FORMING OF THREADED HOLES IN THIN PLATES

S u m m a r y

This paper presents an investigation of the influence of machining data and workpiece thickness on drilling forces and moments during holes and treads forming in thin plates along with a multifactor linear regression analysis of the results. The research allows to predict optimal parameters for holes and treads forming in thin plates in order to optimise the drilling and tapping force along with the torque and, as a consequence, to decrease tool wear and extend the lifetime of the tools.

Keywords: friction drilling, fluteless tapping, thin plate, regression analysis.

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