

Concave Design for High-Moisture Corn Ear Threshing

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crossref <http://dx.doi.org/10.5755/j01.mech.24.1.18345>

1. Introduction

The varieties of corn grown in recent times can be classified into two groups: corn for silage and corn for grain. In the first case, the entire corn crop is harvested with forage harvesters, whereas in the second case (with combine harvesters), cobs are pulled off the stalks by strippers attached to the header and then threshed by a tangential or axial threshing device [1]. With the threshing device being the core unit of a combine harvester, its performance directly influences the quality of corn harvesting [1]. Although the axial threshing device has a greater throughput compared with a tangential device [2, 3] and is characterised by less damage to the grain [4], combine harvesters with a tangential threshing device tend to be common in more humid climate zones [3]. Moreover, a tangential threshing device, which is used in conventional and hybrid combine concepts, is known for its high installation space and energy efficiency [5].

In the U.S. and Western European countries, corn for grain production is traditionally harvested when the grain moisture content reaches approximately 18–25% [6]; hence, combine harvesters have been designed to harvest corn of such a moisture content. High moisture corn ear processing operations have not been extensively explored. In countries with a more humid climate, including the Baltic States, corn ears are harvested in the second half of October and sometimes as late as after the first frost, when grain dry matter content is lower than 65% [7]. Although corn grain reaches physiological maturity at 35% moisture [6, 8], corn plants cultivated for grain production should be harvested when the grain moisture content does not exceed 28% [9]. At crop moisture of over 28% w. b., grain becomes softer and can be squeezed very easily, leading to greater grain damage [2]. Mechanical damage to grain at harvest is mostly caused by field threshing, which is largely due to a high moisture content. Studies have shown that minimum grain damage during corn ear threshing is registered at moisture contents between 20% and 22% [10].

Key evaluation factors of combine harvester operations during corn ear harvesting include grain loss and

grain damage [11]. The following harvest losses at optimum combine adjustment are generally considered acceptable: header ear loss – 1.0%, header grain loss – 0.4%, cylinder or threshing loss – 0.3% and cleaning shoe loss – 0.1% [12]. Moreover, less than 20% of the threshed grains should be thrown to the straw walker [7]. Reducing ground speed helps reduce grain loss by allowing more time for separation of grain and residue [13]. Although combine manufacturers continue to make combine adjustments that are easier to perform, operators must make proper adjustments to ensure that total grain losses are below 5%. In practice, the time spent evaluating and optimising harvest equipment loss efficiency can make a difference to profit margins [12].

Covering clearances between adjacent cylinder rasp bars prevent corn ears from entering the cylinder and plant particles and soil from accumulating in the cylinder, thus avoiding any cylinder imbalance. It has been asserted that when threshing high moisture corn, concave inserts can be used to avoid losses from reduced threshing [12], to help reduce loads on the cleaning shoe and to increase threshing performance in cases of high moisture corn that is hard to thresh. Inserts also prevent broken cob pieces with unthreshed grains from falling through the concave onto the cleaning area. On the other hand, inserts reduce the active separation area of the concave.

High moisture content corn is more susceptible to mechanical damage from machinery during harvest [2]. Ferreira et al. [8] claimed that a progressive increase in mechanical damage to grains (caused by the rotation of the threshing cylinder) as moisture content increases at harvest contributes to a decrease in grain physiological potential and an increase in the occurrence of fungi during grain storage. Majority of the research on threshing has demonstrated that high cylinder speed is the main factor causing grain damage [13, 14]. Other combine harvester parameters such as cylinder-concave clearance and type of cylinder bar seem to affect grain damage only slightly [15]. Grain detachment from the corn cob starts at a cylinder rasp bar speed of 7 m s^{-1} , and grain damage occurs as soon as the rasp bars reach a speed of 14 m s^{-1} [16]. The feed into the threshing device is

formed of non-uniform corn ears of different moisture contents, and the cylinder rasp bar speed should be adjusted to provide proper threshing of more humid corn ears. Grain damage has been found to increase from 3.9% to 6.1% at a 20.3 kg s^{-1} corn ear feed rate into the threshing device and variation of the rasp bar speed from 16.9 to 21.4 m s^{-1} [4]. The damage to grains subjected to a dynamic loading depends on their elasticity modulus [17]. Moreover, deformation of corn ear parts and grain detachment from cobs have been found to depend on the elasticity modulus of the corn ear grains and cobs [18]. It has been claimed that rational cylinder rasp bar speeds range between 10 and 20 m s^{-1} [3], and that grain damage may be reduced by changing the clearance between the cylinder rasp bars and the concave crossbars [19].

The efficiency of the threshing process has been found to depend on the geometrical shape of the concave crossbars [18]. As part of the preparation of combine harvesters for corn ear harvesting, the threshing device concave is replaced with a special concave with rounded crossbars [4]. The clearances between the crossbars may vary from 45 to 80 mm , depending on the concave's manufacturer. During the threshing process, concave crossbars serve as supports for corn ears subjected to impact by rasp bars, thus reducing the rate at which corn ears move over the concave surface and increasing threshing efficiency. Corn ear diameter tends to decrease during threshing, and the clearance between the cylinder rasp bars and concave crossbars is also expected to decrease along the concave length [15, 20]. The recommended clearance between the cylinder rasp bars and the first concave crossbar is about 10 mm smaller than the average ear diameter, whereas at the last concave crossbar, it is equal to, or slightly smaller than, the average cob diameter [7]. In view of the corn ear biometrics, clearance between the cylinder rasp bars and concave crossbar at the end of the concave is recommended to be 15 mm smaller than the clearance at the beginning of the concave [21]. Some researchers have suggested that a rational concave clearance is $35\text{--}40 \text{ mm}$ at the beginning and $18\text{--}20 \text{ mm}$ at the end [22], while some have suggested $25\text{--}30 \text{ mm}$ at the beginning and $15\text{--}20 \text{ mm}$ at the end [3, 14]. A number of researchers have analysed corn ear threshing using tangential threshing devices of different designs, process parameters, ear feed rates and biometrics, resulting in considerably different clearances being recommended for the beginning and end of the concave.

Grain damage can possibly be reduced by redesigning the threshing mechanism, which includes both the cylinder and the concave, so that the shelled grains can leave the threshing crescent immediately after shelling [23]. Previous research has demonstrated that an increase in concave rod spacing tends to reduce the threshing unit loss [24]. This concurs with the research by Norris and Wall [25] who found that when the concave rod spacing was increased from 21 to 30 mm , shelled grains pass through the concave with more ease, leading to a 24% decrease in grain damage and a 38% increase in grain separation efficiency. The concave surface line of certain combine harvesters corresponds to a circular arc. As a result, the reduction of clearance between the cylinder rasp bars and the concave crossbars is non-uniform along the concave length [20, 26]. During grain harvesting, the clearance between the cylinder rasp bars and concave is subject to variation within a narrow

range [3], and non-uniform variation of this clearance insignificantly affects the qualitative performance indicators of threshing. In corn ear harvesting, the clearance is about three-fold larger than that applied in grain harvesting. A designed concave characterised by its surface line approximating Archimedes' spiral would lead to more uniform clearance variation [20, 26]. Nonetheless, its influence on qualitative corn ear threshing indicators has not yet been studied. A non-uniform variation in the clearance between the cylinder rasp bars and concave crossbars could lead to variation in the ear movement rate and the number of their interactions with rasp bars; in turn, this could cause grain damage and impact grain separation in the concave.

This work aims to determine the influence of concave shape and crossbar layout on (i) the behaviour of humid corn ears during threshing and (ii) the qualitative performance indicators.

2. Materials and methods

2.1. Biometric indicators

Thirty corn ears were random selected by triplicate sampling of a stock of handpicked corn ears (*Rodni* variety). Each corn ear was weighed separately, and husk leaves were removed from the ears and weighed. The lengths of each corn ear and the diameter variation along the ear length were determined, and the number of grains in vertical rows and horizontal rings were counted. Following grain separation from each corn cob, the grains and the cob were weighted separately. Cob length and diameter variation along its length were measured. Arithmetic averages and confidence intervals were calculated for each ear sample. Ear grains, cobs and husk leaves were oven dried at 100°C for 72 hours for moisture content determination.

2.2. Test bench

Experimental trials were conducted in the laboratory by threshing high moisture corn ears (grain moisture content of $36.16\% \pm 1.83\%$). Ears were fed by belt conveyor 1 (Fig. 1) into a threshing device consisting of 10 rasp bars, cylinder 2 (800 mm diameter and 1500 mm wide) and concave 3. The test bench was driven by a 30 kW electric motor. The threshing cylinder rotation frequency was held constant (350 min^{-1}) by a voltage frequency converter *Delta VFD-C2000 SERIES* and a cylinder gear variator.

This study involved comparative experimental trials of two concaves with different shapes. The surface line of the control concave (conventional design) corresponds to a portion of a circular arc (Figs. 2, b, d and f), whereas the experimental concave corresponds to a portion of Archimedes' spiral (Figs. 2, a, c and e). Both concaves provide the option of adjusting the clearance between adjacent crossbars (45.0 , 62.5 and 80.0 mm); in turn, the number of crossbars and the active separation area can also be adjusted (Table 1). Half of the crossbars in the first section of each concave were rectangular (8 mm wide and 9 mm high above the concave rods); the remaining crossbars had similar dimensions but were rounded ($r = 4 \text{ mm}$). At the beginning of both concaves, a 36.0 mm clearance was set between the first crossbar and the cylinder rasp bar; this clearance was 22.0 mm at the end. The measurement of clearances between the cylinder rasp bar and control concave crossbars showed that the

clearance increased from 36.0 to 48.1 mm up to the ninth crossbar, was 44.9 mm at the twelfth crossbar and was

22.0 mm at the end of the concave, with the clearance between adjacent crossbars being 45.0 mm.

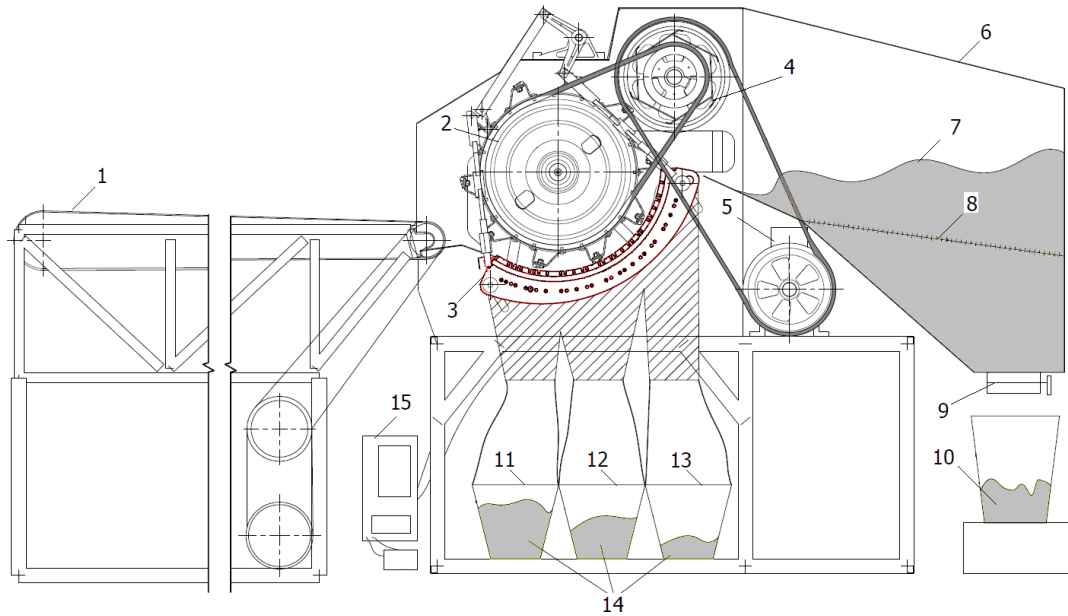


Fig. 1 Test bench for corn ear threshing [18]: 1 – belt conveyor; 2 – threshing cylinder; 3 – control or experimental concave; 4 – beater cylinder; 5 – electric motor; 6 – threshed matter container; 7 – threshed matter; 8 – sieve; 9 – valve; 10 – grain; 11–13 – containers; 14 – grain with impurities; 15 – voltage frequency converter

For the experimental concave, the clearance decreased consistently along the concave arc length and was 24.6 mm at the ninth concave crossbar, 22.7 mm at the twelfth crossbar and 22.0 mm at the end of concave. It should be noted that the experimental concave arc was 65.00 mm shorter; therefore, the experimental concave had one less crossbar than the control concave. The wrap angle of both concaves around the cylinder was the same at 123° ,

with a clearance equal to 36–22 mm. The wrap angle of the concave around the cylinder decreased when the clearance increased. The clearance between the cylinder and experimental concave may also be adjusted in view of the ear diameter. In this case, uniform variation of the concave would not be observed; however, the deviation would not be significant.

Table 1

Concave parameters

Concave arc shape		Total concave area A , m^2	Active separation area A_s , %	Concave arc length L , m	Concave arc angle α , $^\circ$	Wrap angle of concave around cylinder β , $^\circ$	Clearances between crossbars l , mm	Number of crossbars	Number of rounded crossbars in the second section of concave
Experimental	Fig. 2, a	1.34	56.7	0.910	120	123	45.0	18	8
	Fig. 2, c		59.1				62.5	14	7
	Fig. 2, e		60.3				80.0	12	6
Control	Fig. 2, b	1.39	56.5	0.975	130		45.0	19	9
	Fig. 2, d		58.8				62.5	15	7
	Fig. 2, f		60.0				80.0	13	6

2.3. Analysis of corn ear movement over the concave surface

Corn ear behaviour in the clearance between the cylinder and the concave was recorded by high-speed video camera (*Photron Fastcam 1024PCI*; *Photron, Japan*) at a frame rate of 2000 f s^{-1} . Corn ears were placed one by one on a special tray bottom and then rolled parallel to the threshing cylinder shaft into the clearance between the cylinder rasp bars and the first concave crossbar. The time to

the start of ear movement over the surface of the first concave crossbar after contact between the ear and the cylinder rasp bar, and the time to the fall of the threshed ear off the concave, was recorded. Analysis of the video material demonstrated the variation in ear position during its movement in the clearance between the cylinder rasp bars and the concave, as well as the duration of the movement, the average movement rate and the number of impacts between the rasp bars and the ear.

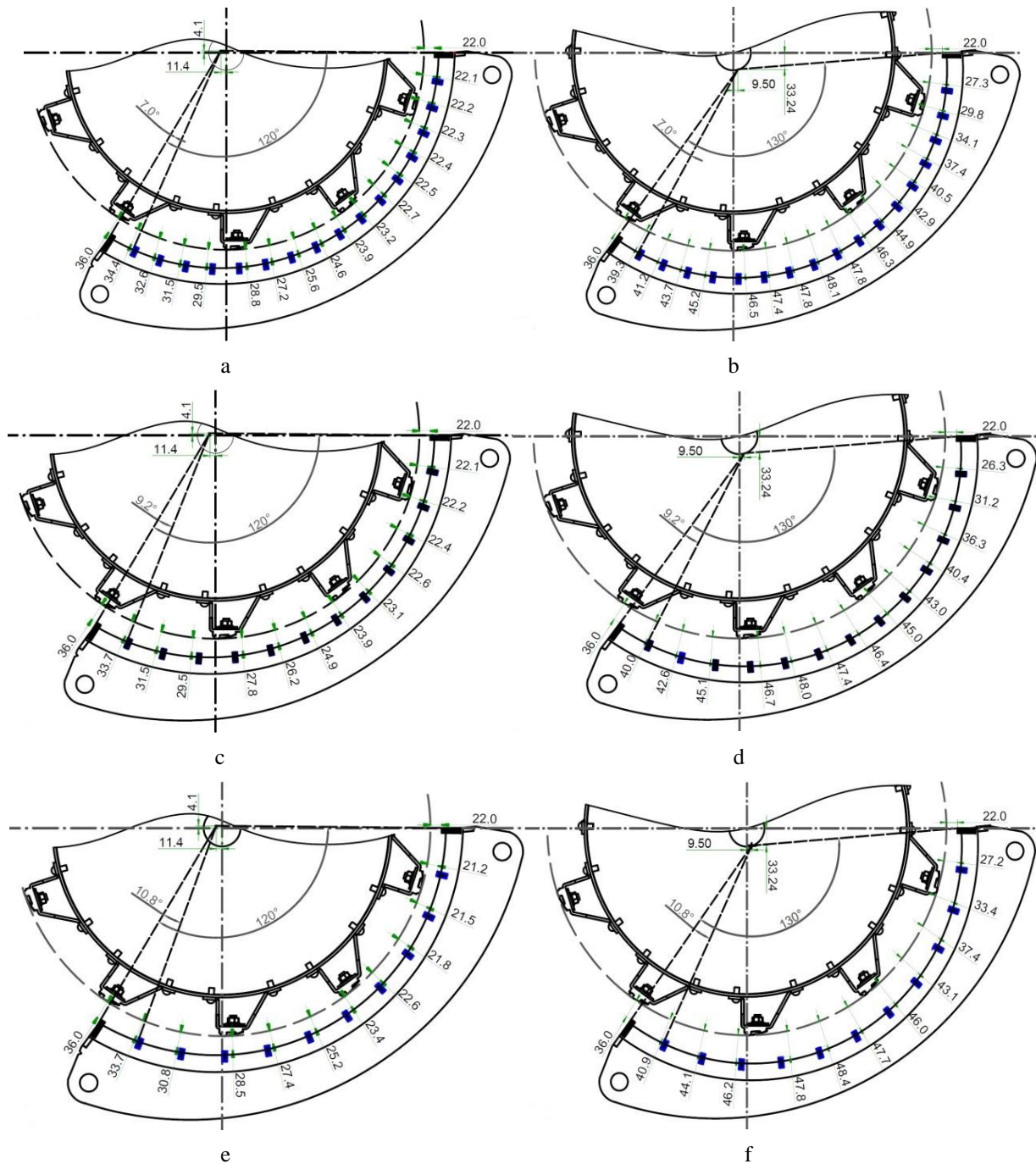


Fig. 2 Shapes of concaves used for the trials: a, c, e – experimental concave; b, d, f – control concave (Table 1)

2.4. Amount of ears fed into the threshing device and performance indicators of the threshing process

Corn ears were fed into the threshing device at a speed of 1 m s^{-1} by the 10 m long belt conveyor (Fig. 1). The total mass fed into the threshing device was varied from 5.6 to 20.6 kg s^{-1} by spreading different masses of ears on a 7 m length of the belt conveyor. Three sections characterised by equal areas were identified as the concave of the threshing device (Fig. 1). During corn ear threshing, threshed grains that passed through the concave sections entered containers 11, 12 and 13. The threshed grains were weighed using an electronic scale (CAS DB-1H; CAS, South Korea). The portion of coarse impurities in the grain was determined by sieving the threshed grain through a 5 mm mesh. Impurities remaining on the sieve and the grain that had passed through the sieve were weighed separately; their

amounts demonstrated grain separation through the concave. Threshed matter (corn cobs, leaves and threshed grain not separated through the concave) 7 that dropped off the concave end due to the threshing cylinder rasp bars and beater cylinder 4 blades was collected in a separate container 6. Grains that passed through the sieve 8 in the threshed matter container and collected in the container were weighed separately. The masses of these grains allowed calculation of the grain separation loss in the threshing device. Grain loss at threshing was calculated by the detachment of non-threshed grain from each corn cob and its weighing by an electronic scale Kern CM 320-1N (Kern, Germany). Five 100 g samples of grain that had fallen through each concave section were taken. Mechanically damaged grains were separated from each sample and weighed. The average percentage of damaged grains was calculated.

2.5. Power consumption

The active power required for rotation of the threshing cylinder was measured simultaneously using two electric power system analysis devices: *ME-MI2492* (*Metrel, Slovenia*) and *Almemo 2890-9* (*Ahlborn, Germany*) [18].

2.6. Statistical analysis

The experiments were carried out with three or four replicates. Regression and correlation analyses were used to evaluate the results. A 0.05 probability level was used as the criterion for tests of significance throughout the data analysis.

3. Results and discussion

Key quality indicators of the corn ear threshing process are grain damage, grain threshing loss and grain loss from separation through the concave. These indicators de-

pend on design and process parameters of the threshing device, biometric indicators of the corn ears and the amount of ears fed into the threshing device [11, 12].

3.1 Biometric indicators of corn ears

During threshing, the average grain moisture content of the corn ears (Table 2) was $36.16\% \pm 1.83\%$, while those of the cobs and husk leaves were $61.94\% \pm 7.52\%$ and $64.63\% \pm 6.83\%$, respectively.

The grain moisture content variation along the corn ear length was given by:

$$w = -0.0011 n^2 - 0.147n + 37.76; R^2 = 0.94, \quad (1)$$

where: n is the number of grain rows along the ear length (Table 2).

Grain with the highest moisture content was found to concentrate at the ear end. This is because the cob is attached to the stalk at the node and the moisture content of the stalk was about 20% higher than that of the cob. Moreover, its diameter along the ear length of 0–84 mm and its 1000 grain mass are the largest.

Table 2

Biometric indicators of corn ears

Indicator	Unit of measurement	Average value (\pm confidence interval values at 95% probability)
Corn ear mass	g	225.13 ± 12.36
Maximum corn ear diameter	mm	45.89 ± 0.79
Corn ear length	mm	173.56 ± 3.55
Number of grains	pcs	476.70 ± 18.36
Grain mass (14% moisture content)	g	120.00 ± 8.08
Number of vertical rows in the corn ear	rows	13.77 ± 0.41
Number of horizontal rows in the corn ear	rows	35.47 ± 0.98
Maximum cob diameter	mm	28.36 ± 0.53
Cob mass (18% moisture content)	g	19.89 ± 13.10
1000 grain mass (14% moisture content)	g	245.03 ± 8.73

Researchers have claimed that the correct cylinder speed and concave clearance adjustment may reduce threshing losses to 0.3% or less [12]. Grain losses during threshing should be reduced by altering concave clearance since the impact of the concave on grain damage is low compared

with an increase in cylinder peripheral velocity [22]. In view of the different diameters of the corn ears fed into the combine harvester, diameter variation along the corn ear length was determined to evaluate the effect of the clearance between the cylinder rasp bars and the concave (Fig. 3).

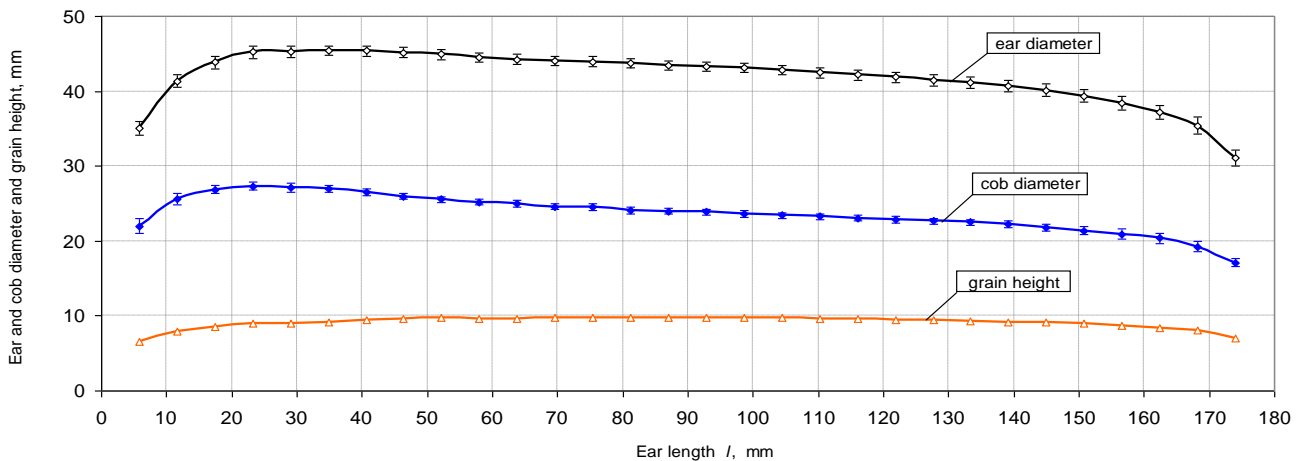


Fig. 3 Variations in corn ear diameter, cob diameter and grain height along the ear length

The maximum diameter of corn ears with 14 vertical grain rows was 45.89 ± 0.79 mm, while the average grain height was 9.8 ± 0.2 mm. In view of the diameter variation along the corn ear length, and based on the recommendations by other authors [7], a 36 mm clearance between the first concave crossbar and cylinder rasp bars and a 22 mm clearance at the end of concave, were set during the trials. The clearance between the cylinder rasp bar and the first concave crossbar (36 mm) was determined as follows: maximum corn ear diameter (45.89 ± 0.79 mm) minus the average grain height (9.8 ± 0.2 mm). The clearance between the cylinder rasp bar and the last concave crossbar (22 mm) was determined by adding half of the average grain height (4.9 ± 0.1 mm) to the smallest cob diameter (17.15 ± 0.22 mm).

3.2. Corn ear movement and behaviour in the clearance between cylinder rasp bars and concave

Corn ear behaviour in the clearance between the cylinder rasp bars and the concave crossbars depends on the diameter variation along its length and its position with respect to the first concave crossbar, whereas grain detachment from the cob depends on the strength of the grain bond

to the cob [7, 10]. Concave surface line variation equations were developed in view of the ear dimensions and were based on the assumption that the clearance between the cylinder rasp bars and concave crossbars at the beginning and end of the threshing device is 36 mm and 22 mm, respectively, for the both control and experimental concaves. The analysis of threshing devices is possible with the mathematical description of the curve characteristic over the separation length [5]. In this study, an 800 mm diameter threshing cylinder was used for the trials of both concaves. Its circumference equation with respect to the centre O (x_o, y_o) in the Cartesian coordinate system was generated, yielding the following coordinates (Fig. 4):

$$\begin{cases} x = x_o + r \cos\varphi \\ y = y_o + r \sin\varphi \end{cases}, \quad (2)$$

where: r is the cylinder radius set at $r = 400$ mm and φ is the cylinder circumference line angle at a chosen point that varies from 0 to 2π .

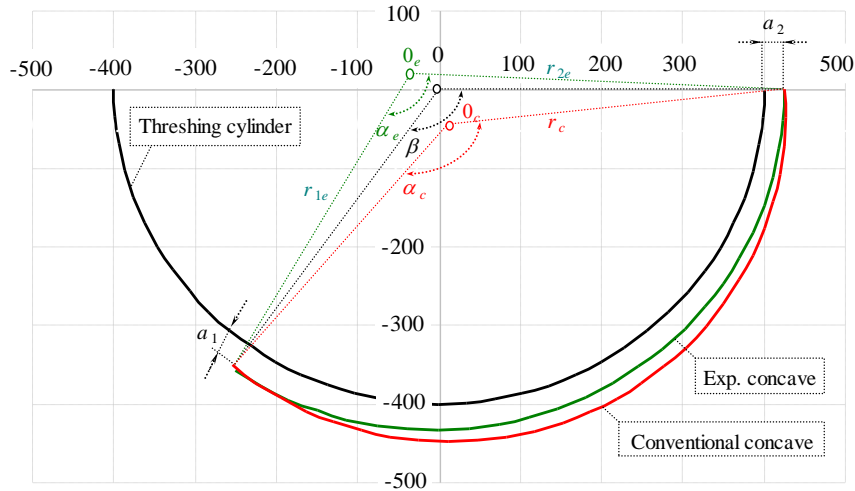


Fig. 4 Surface shapes of the experimental and control concaves in the Cartesian coordinate system: $O(x_o, y_o)$ – cylinder centre with the coordinates, $O_c(x_{oc}, y_{oc})$; $O_e(x_{oe}, y_{oe})$ – convex surface centres of the control and experimental concaves with coordinates; r_{1e}, r_{2e} – distances of experimental concave from the centre $O_e(-11.4$ and 4.1 mm) at the beginning and end of the threshing device; r_c – distance of control concave from the centre $O_c(9.50$ and -33.24 mm); a_1 – clearance between the cylinder and concave in the front part of the threshing device, $a_1 = 36$ mm; a_2 – clearance between the cylinder and concave in the rear part of the threshing device, $a_2 = 22$ mm; α_e – arc angle of the experimental concave, $\alpha_e = 120^\circ$; α_c – arc angle of the control concave, $\alpha_c = 130^\circ$; β – wrap angle of concave around the cylinder, $\beta = 123^\circ$

The control concave wrap line equation relative to the cylinder centre O (x_o, y_o) was generated, yielding the following coordinates for the control concave:

$$\begin{cases} x_c = x_{oc} + r \cos\beta_n \\ y_c = y_{oc} + r \sin\beta_n \end{cases}, \quad (3)$$

where: x_{oc} and y_{oc} are the coordinates of the arc centre of the control concave relative to the cylinder centre O (x_o, y_o) set at values $x_{oc} = 9.50$ mm and $y_{oc} = -33.24$ mm and β_n is the wrap angle of concave around the cylinder at a chosen point that varies from 236° to 360° .

The wrap line equation for the experimental concave relative to the cylinder centre O (x_o, y_o) was generated,

yielding the following coordinates for the experimental concave:

$$\begin{cases} x_e = \left(r + a_1 + a_2 - \left(\left(\frac{a_1 - a_2}{\beta} \right) \beta_n \right) \right) \cos\beta_n \\ y_e = \left(r + a_1 + a_2 - \left(\left(\frac{a_1 - a_2}{\beta} \right) \beta_n \right) \right) \sin\beta_n \end{cases}, \quad (4)$$

where: a_1 is the clearance between the cylinder and concave at the beginning of the threshing device set at $a_1 = 36$ mm, a_2 is the clearance between the cylinder and concave at the end of the threshing device set at $a_2 = 22$ mm, β is wrap angle of concave around the cylinder set at $\beta = 123^\circ$ and β_n is

the wrap angle of concave around the cylinder at a chosen point.

Variation in the clearance between the cylinder rasp bars and concave crossbars along the concave length is presented in Fig. 5.

A linear reduction in the clearance between the cylinder rasp bars and concave crossbars was registered from the beginning of the concave to the middle of the experimental concave. Starting with $\beta = 75^\circ$, i.e., the 12th crossbar, the variation in the clearance is insignificant. For the threshing device with the control concave, clearance a increased to 48 mm up to $\beta = 45^\circ$, i.e., the 9th crossbar. Subsequently, there was a gradual reduction. In general, variation in clearance a along the concave length may be defined as a convex parabola. This increase in clearance a is unreasonable during threshing as a corn ear with an initial diameter of about 46 mm is subjected to partial threshing at its very first impact with the rasp bars, which causes its diameter to decrease. As a result, a corn ear that enters a larger space is not effectively acted upon by the rasp bars and its movement rate may decrease, potentially subjecting the threshed grains to additional damage. These assumptions were verified in this work by experimental trials involving the analysis of corn ear movement using a high-speed video recording method that has been previously applied in similar studies [7, 10, 15].

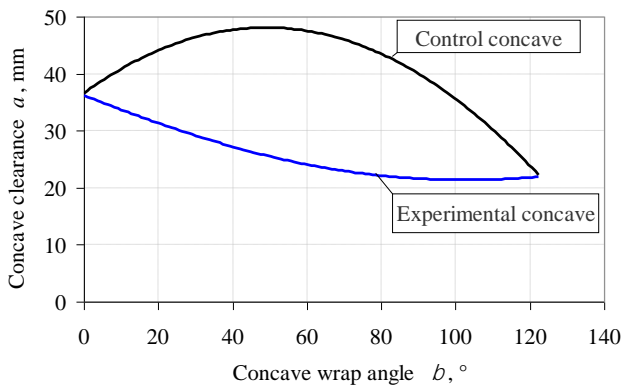


Fig. 5 Variation in clearance between cylinder rasp bars and concave crossbars

In a combine harvester, corn ears are fed into the threshing device by a scraper conveyor. Majority of the corn ears lie parallel to the cylinder shaft at the first concave crossbar. High-speed video analysis showed that the average corn ear movement rate was $6.12 \pm 0.99 \text{ m s}^{-1}$ in the first third of the concave and $4.28 \pm 0.67 \text{ m s}^{-1}$ in the middle of the concave (Table 3) during the threshing of single ears (with the threshing cylinder rotated at a rate of 350 min^{-1} , and the clearance between the cylinder rasp bars and control concave rectangular crossbars set at 36–22 mm) due to a considerable increase in the clearance between the cylinder rasp bars and concave crossbars (Fig. 5). The average corn ear movement rate in the clearance between the cylinder rasp bars and the concave was $4.76 \pm 0.48 \text{ m s}^{-1}$. Each corn ear was subjected to nine or 10 contacts with the cylinder rasp bars. Where a moving ear, acted upon by rasp bar impacts, was rotated and became perpendicular to the concave crossbars, its movement rate decreased further in the middle

section of the concave (to $2.20 \pm 0.44 \text{ m s}^{-1}$). In this case, the average ear movement rate in the clearance between the cylinder rasp bars and concave was decreased to $3.78 \pm 0.29 \text{ m s}^{-1}$. Each corn ear had about 10 contacts with the cylinder rasp bars; however, these contacts were inefficient in the middle section of the length, especially as the rasp bars often either only just touched, or did not touch, the top of the corn ear. Crossbar shape did not have any significant effect on corn ear movement rate, i.e. the trends referred to above were also found when using the concave with rounded crossbars (Table 3).

When corn ears entered the threshing device in a position perpendicular to the concave crossbar, they were subjected to impact, bending and slight forward pushing by the cylinder rasp bars. Corn ears were often broken into two halves, each of which moved randomly. On certain occasions, the onset of corn ear movement necessitated its pushing by a following ear. The movement of certain ear cobs with non-threshed grains in the middle of the concave (the section characterised by the largest clearance between the cylinder and concave) was decreased, or even stopped, as they did not contact the cylinder rasp bars. The average movement rate of corn ears moving perpendicular to the concave crossbars varied across a very wide range, and the corn ears had eight to 15 contacts with the cylinder rasp bars. The results of these trials support the arguments put forward in former studies; namely that (i) maximum grain damage is incurred by ears fed with their axis perpendicular to the cylinder axis [10], and (ii) corn ears that enter the threshing device orientated in this way move at half the speed and their cobs are broken into several parts, becoming threshed only if the clearance is reduced to 29–8 mm due to the greater number of impacts by the rasp bars [7].

Considering that the threshing device with the experimental concave demonstrated a uniform reduction in clearance between the cylinder and concave (Fig. 5), corn ears moving over the concave surface tended not to change their orientation with respect to the crossbars. The majority of corn ears moving towards the end of the concave lay parallel to the concave crossbars. Compared with the control concave, the corn ears moved at a more constant rate; the average rate in the first section of the concave was $6.04 \pm 0.47 \text{ m s}^{-1}$, in the middle of the concave was $5.40 \pm 0.36 \text{ m s}^{-1}$ and at the end of the concave was $5.02 \pm 0.42 \text{ m s}^{-1}$ (Table 3). The average movement rate of corn ears ($5.48 \pm 0.25 \text{ m s}^{-1}$) was higher than the rate of corn ears moving over the control concave. Each corn ear had seven or eight contacts with the cylinder rasp bars, but these contacts were more effective than those of the control concave.

In general, it may be asserted that the trials on corn ear movement duration in separate sections of the concave (i.e. movement rate and number of impacts) have substantiated the need for further studies (e.g. studies on corn ear flow) as the corn ear movement rate in the second and third sections of the control concave arc length were shown to decrease considerably. This occurred despite a greater number of impacts because these impacts were inefficient. The experimental concave used for corn ear threshing may help to avoid the reduction in movement rate. In this case, it is likely that humid corn ears would be fully threshed more rapidly and the grain would be subjected to less damage.

Indicators of corn ear movement in the threshing device with confidence interval values at 95% probability (clearance between crossbars $l = 62.5$ mm)

Concave and crossbar shape	Corn ear movement duration by concave sections t , s				Corn ear movement rate v , m s ⁻¹			
	Section I	Section II	Section III	Along entire concave arc length	Section I	Section II	Section III	Along entire concave arc length
Rectangular: control	0.058±	0.083±	0.088±	0.229	6.12±0.99	4.28±0.67	4.05±0.60	4.76±0.48
	0.010	0.012	0.014					
experimental	0.056±	0.058±	0.067±	0.181	6.04±0.47	5.40±0.36	5.02±0.42	5.48±0.25
	0.003	0.004	0.005					
Rounded: control	0.051±	0.076±	0.074±	0.201	6.60±0.58	4.46±0.72	4.95±0.72	4.86±0.41
	0.005	0.010	0.015					
experimental	0.054±	0.058±	0.057±	0.169	6.00±0.54	5.62±0.46	5.69±0.48	5.77±0.27
	0.005	0.004	0.005					

3.3. Grain threshing losses

The corn ear feed rate is known to be one of the most important factors influencing the combine harvester's performance [27]. Correct threshing device adjustment is achieved when grains are removed from the cobs and the cobs are not broken [12]. In the present study, in the case of the control concave with the largest (80.0 mm) clearance between the crossbars (Fig. 6) and the corn ear flow into the threshing device increased from 5.6 to 20.6 kg s⁻¹, the grain threshing loss increased from 0.6% to 3.0%. For these values, the acceptable limit of grain threshing loss (0.3%) was exceeded by 2 to 10 fold, respectively.

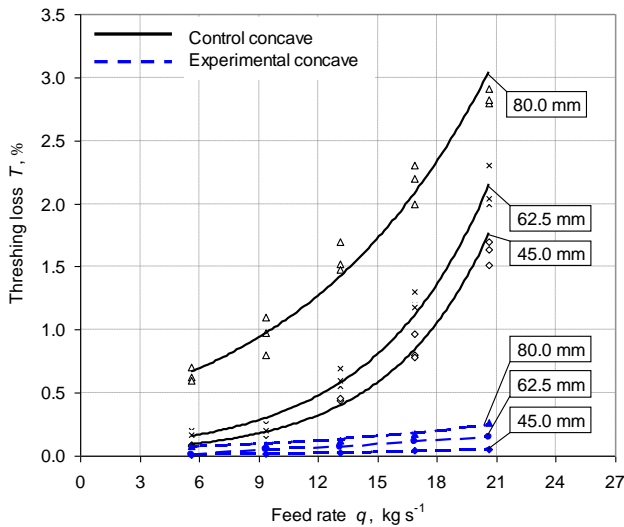


Fig. 6 Influence of concave shape and clearance between crossbars on grain threshing loss

It was noted that the largest portion of non-threshed grains remained on the tips of broken ear cobs. Following the reduction of the clearance between the concave crossbars to 62.5 mm (the concave had 15 crossbars), grain threshing loss was reduced; however, it exceeded the acceptable loss at a corn ear feed rate above 10 kg s⁻¹. Further reduction of the clearance to 45.0 mm, i.e. an increase in the number of crossbars to 19, did not yield a significant reduction in loss. In comparison, Norris and Wall [25] stated that eight concave crossbars are sufficient for full threshing of dry corn ears, but this requires increasing the height of the

concave bars above the concave rods to 13 mm. In the case of the experimental concave in the threshing device, grain threshing loss did not exceed the acceptable limit irrespective of the clearance between adjacent concave crossbars and of the corn ear feed rate.

In general, it can be asserted that the experimental concave helps reduce grain threshing loss below the acceptable limit even at a corn ear feed rate of 20 kg s⁻¹. Moreover, reduction of the clearance between crossbars (from 80 to 45 mm) in the control concave was found to have a considerably greater positive effect on grain threshing loss, as compared with the experimental concave.

3.4. Loss of grain separation through concave

One of the key performance indicators of the corn ear threshing process is grain separation loss, i.e. grain that has been threshed but not passed the concave. Petkevichius et al. [7] stated that with correct adjustment of the threshing apparatus, separation loss should not exceed 20% of the grain feed rate. Grain separation loss in the threshing device is known to be considerably reduced by increasing the concave length, i.e. the separation area [28, 29]. The present study has determined that concave shape does influence grain separation loss. In the case of the control concave (conventional design), with the ear feed rate q increased from 5.6 to 20.6 kg s⁻¹, 15.1% to 23.3% of the grains reached the straw walkers, respectively, whereas in the case of experimental concave, 4.7% to 12.6% of the grains reached the straw walkers, respectively. Separation of the threshed grain through the concave grating can be increased two-fold (on average) using the experimental concave (Fig. 7). Moreover, the concave shape has been found to have no significant influence on the cleanness of grain falling through the concave (Table 4).

An increase in the clearance between the crossbars (from 45 to 80 mm) influenced grain separation through the control concave only and only for corn ear feed rates above 12 kg s⁻¹.

In general, it can be asserted that adjustment of concave shape may considerably reduce portion of grain threshed that ends up on the straw walkers, i.e. the separation loss. Moreover, concave shape does not have a significant influence on the cleanness of grains passing through the grating of the concave.

Effect of concave shape on the proportion of impurities P in the mass separated through the concave with confidence interval values at 95% probability

Concave	Clearance between crossbars l , mm	Section I of the concave P_1 , g	Section II of the concave P_2 , g	Section III of the concave P_3 , g
Experimental	45.0	1.18 ± 0.35	1.36 ± 0.28	1.61 ± 0.36
	62.5	1.62 ± 0.36	1.69 ± 0.44	1.76 ± 0.34
	80.0	1.98 ± 0.25	2.26 ± 0.39	2.41 ± 0.32
Control	45.0	1.04 ± 0.57	1.49 ± 0.42	2.32 ± 0.66
	62.5	1.34 ± 0.17	1.61 ± 0.21	2.48 ± 0.58
	80.0	1.79 ± 0.23	1.92 ± 0.20	3.05 ± 0.69

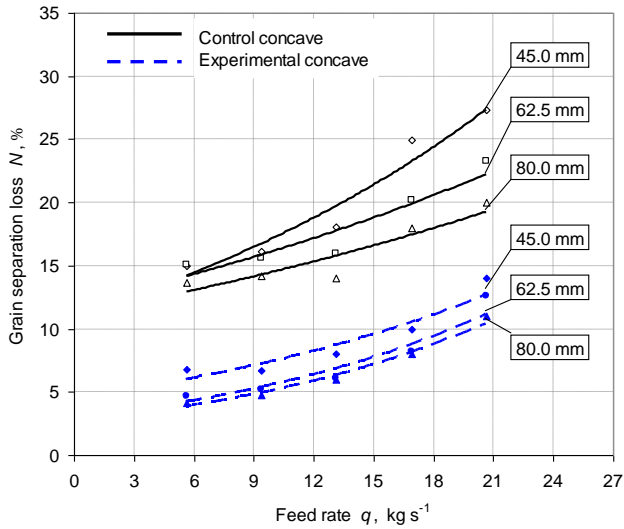


Fig. 7 Influence of concave shape and clearance between crossbars on separation loss through the concave (each point on the graph is the arithmetic average of three replications)

3.5. Grain damage

Excessive threshing has been reported to result in low threshing losses and greater grain damage [12, 30]. Experimental results by a number of researchers indicated that the moisture content of grain has a significant influence on grain breakage [7, 10, 17, 30, 31].

The portion of grain subjected to damage was consistently reduced with an increase in corn ear feed rate from 5.6 to 20.6 kg s^{-1} for both the control and experimental concaves (Fig. 8). Nevertheless, more grains were subjected to damage in the threshing device with the control concave. This was influenced by variations in corn ear movement rate, the number of contacts between the corn ears and rasp bars and the clearance between the cylinder rasp bars and concave crossbars. For the threshing device with the control concave, the clearance between the crossbars and cylinder rasp bars initially increased, before decreasing. On the other hand, for the experimental concave, the clearance consistently decreased along the concave length. As a result, the number of contacts between the cylinder rasp bars and corn ears was twice as high in the threshing device with the control concave.

An increase from 45.0 to 62.5 mm in the clearance between the crossbars in the experimental concave resulted in an average grain damage that did not exceed the acceptable limit of 3% (Fig. 8). However, in the control concave,

only at a corn ear feed rate of 20.6 kg s^{-1} was the acceptable loss not exceeded. In both concaves, the acceptable limit of damaged grain was not exceeded upon increase of the clearance between the crossbars to 80 mm, irrespective of the corn ear feed rate.

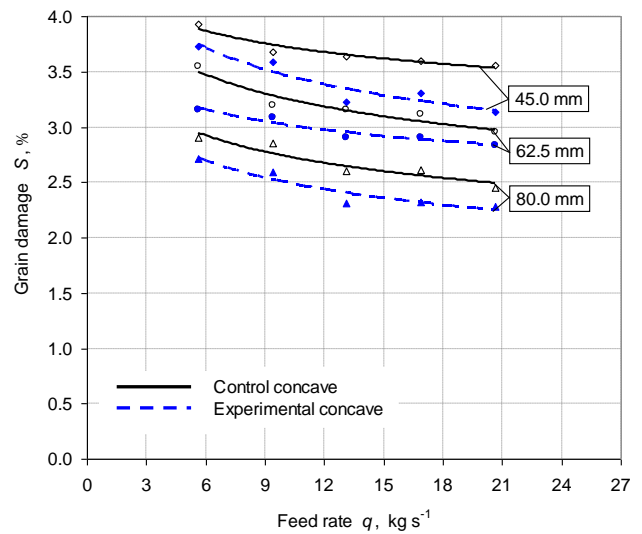


Fig. 8 Influence of concave shape and clearance between crossbars on grain damage (each point in the graph is the arithmetic average of three replications)

The consistency of the corn ear threshing process is characterised by grain separation variation along the concave length [20]. In the present study, variation in grain separation through sections of the control and experimental concaves was compared by adjusting the corn ear feed rate into the threshing device at a 62.5 mm clearance between the concave crossbars. At a corn ear feed rate into the threshing device of 20.6 kg s^{-1} , 35.23% \pm 1.53% of the grain fell through the first section of the control concave, and 42.13% \pm 2.29% fell through the first section of the experimental concave (Fig. 9). The difference was even at lower corn ear feed rates. Grain separation through the entire control concave was significantly faster and amounted to 72% of the grain, whereas through the experimental concave, it was 87% of the grain. The intensification of separation, particularly in the first section, reduced grain damage for the experimental concave (Fig. 8). This supports the argument generated by earlier studies; namely that grain damage can potentially be reduced when the shelled grains are expelled from the threshing crescent immediately after threshing [23].

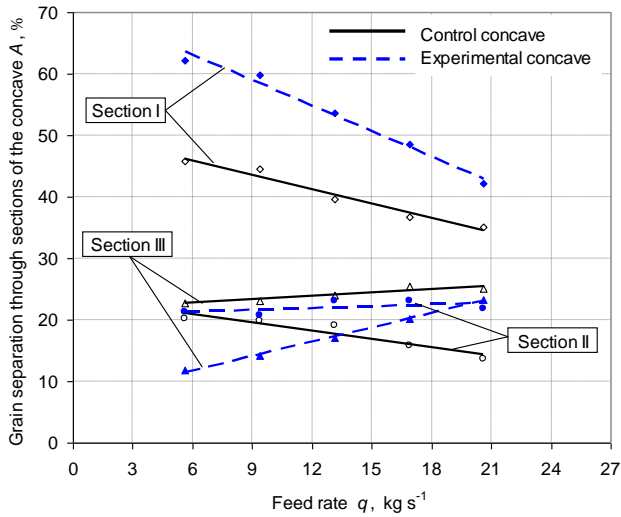


Fig. 9 Influence of concave shape on separation of grain by sections of the experimental concave, where $l = 62.5$ mm (each point in the graph is the arithmetic average of three replications)

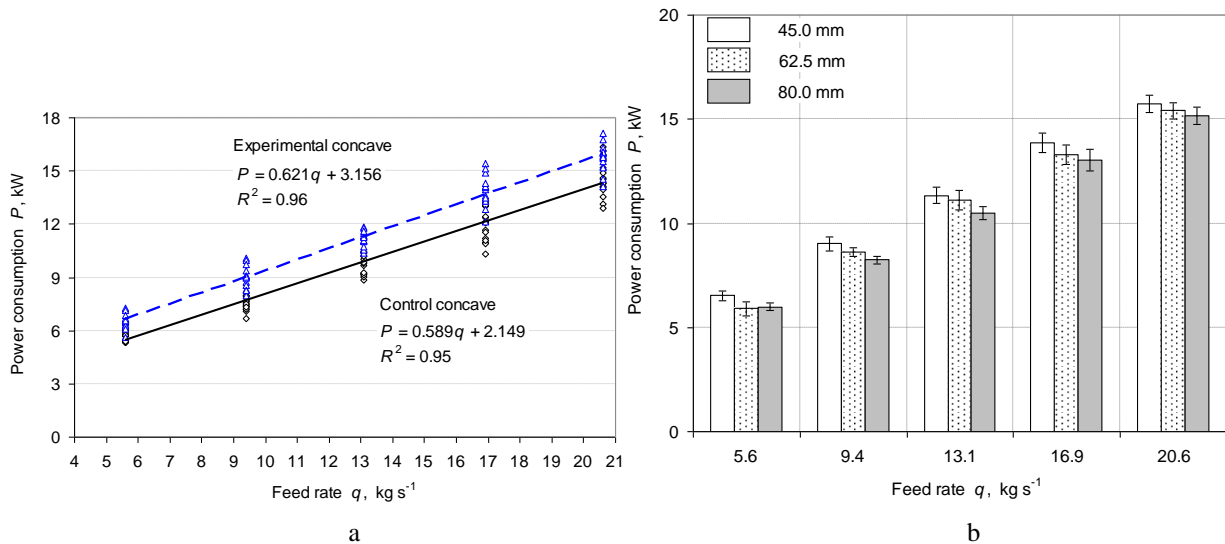


Fig. 10 Dependence of power requirement on (a) the concave shape with a 62.5-mm clearance and (b) clearance between the crossbars of the experimental concave

The detachment of grains from corn ears is accomplished by a combination of impacts and a rubbing action [14]. Impact loads are known to cause more damage to grain than the rubbing action [2, 17]. This is supported by the fact that axial threshing devices cause less grain damage [2]. It would therefore be reasonable for further studies to focus on the installation of diagonal crossbars in the validated experimental concave [18] to ensure that a rubbing action, rather than an impact action, prevails during threshing.

4. Conclusions

1. In the case of correspondence between the control concave surface line and a circular arc, the clearance between the crossbars and cylinder rasp bars from the beginning of the concave to a wrap angle of $\beta = 45^\circ$ increased from 36 to 48 mm, before decreasing to 22 mm. In the case of correspondence between the experimental concave surface line with a portion of Archimedes' spiral, the clearance along the entire length of the concave was reduced from 36

The study results support the use of a rational 62.5 mm clearance between the crossbars in the experimental concave, ensuring that the portion of damaged grain does not exceed the acceptable limit of 3%. Grain damage showed a downward trend with increasing corn ear feed rate. In general, it could be asserted that a considerable increase in grain separation in the first section of the experimental concave is a key factor in grain damage reduction.

3.6. Power consumption

Some studies have already determined that corn ear feed rate influences power, and in turn fuel consumption [24, 32]. This study aimed to determine the additional power requirement of corn ear threshing after replacement of the control concave with the experimental concave. Our results demonstrated that in view of the shape of the experimental concave, about 2 kW of additional power is required, irrespective of the corn ear feed rate (Fig. 10a). It was also determined that an increase in the clearance between the crossbars from 45.0 to 80.0 mm leads to only a minor reduction in the need for power (by about 0.5 kW) (Fig. 10b).

to 22 mm. The difference between these designs controlled the difference in the rate of corn ear movement over the concave surfaces. Corn ear movement rate was subjected to considerable reduction in the second and third sections of the control concave length despite a greater number of impacts, because these impacts were ineffective. A significant rate reduction could be avoided if the experimental concave was used for corn ear threshing.

The average movement rate of a corn ears, entered the threshing device in a position parallel to the concave crossbar, over the control concave surface was 4.76 ± 0.48 m s⁻¹ and the corn ear had nine or ten contacts with the cylinder rasp bars. For the experimental concave, the corn ear average movement rate was 5.48 ± 0.25 m s⁻¹, with seven or eight contacts between the corn ear and the cylinder rasp bars.

2. During the threshing of high moisture (grain moisture content of $36.16\% \pm 1.83\%$) corn ears, with the clearance between the control concave crossbars l set to 62.5 mm, the grain threshing loss amounted to 2.2% (where

$q = 20.6 \text{ kg s}^{-1}$). This loss increased to 2.8% upon an increase of l . For the experimental concave, the dependence of the loss on q and l was insignificant and the loss did not exceed the acceptable limit of 0.3%.

3. The experimental concave enabled about a two-fold increase in threshed grain separation through the concave grating. For the experimental concave, the intensification of separation, particularly in the first section, allowed for a reduction in grain damage of about 0.5 of percentage point in case of the experimental concave. In view of the results on grain damage and separation, a rational 62.5 mm clearance between the crossbars of the experimental concave has been validated, i.e. the portion of damaged grain did not exceed the acceptable limit of 3% at that point. Grain damaged showed a downward trend with increasing corn ear feed rate.

4. The shape of the experimental concave resulted in an increased power requirement of about 2 kW compared with the control concave, irrespective of the corn ear feed rate ($q = 5.4\text{--}20.6 \text{ kg s}^{-1}$). Moreover, an increase in clearance between the experimental concave crossbars from 45.0 to 80.0 mm was found to yield only a minor reduction in the need for power (by about 0.5 kW).

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CONCAVE DESIGN FOR HIGH-MOISTURE CORN EAR THRESHING

S u m m a r y

In a threshing device, identifying the optimum balance between grain damage and grain loss during threshing is highly relevant while harvesting high-moisture corn ears. The qualitative performance indicators of a threshing device depend on the corn ear properties and process parameters as well as the device's design. Comparative experimental trials of two concaves (control and experimental) of a tangential threshing device were conducted under laboratory conditions by threshing high-moisture corn ears. The control concave's surface line corresponded to a circular arc, whereas that of the experimental concave corresponded to a portion of Archimedes' spiral. The clearance between the crossbars and cylinder rasp bars in the first section of the control concave length increased, whereas in the second section, it decreased. For the experimental concave, the clearance along the entire concave length consistently decreased. The experimental concave yielded approximately half the grain loss of the control during separation in the concave. A rational clearance between the experimental concave crossbars was validated because the portion of damaged grain did not exceed 3% at that point. With clearance l equal to 62.5 mm in the control concave, the grain threshing loss was 2.2%, whereas for the experimental concave, the loss was virtually independent of q and did not exceed the acceptable 0.3% limit. In general, the trials demonstrated that for high-moisture corn ear threshing, the surface line of the concave should correspond to a portion of Archimedes' spiral and the clearances between adjacent crossbars should be 62.5 mm.

Keywords: tangential threshing device, ear feed rate, grain separation, grain damage, power consumption.

Received June 09, 2017

Accepted February 15, 2018